

Joint Stock Company Scientific & Production Association **Spetsneftegaz**

> **EMAT** A new capabilities



A new EMAT capabilities



SPETSNEFTEGAZ



UT vs MFL

What is better?





Magnetic flux leakage in-line inspection





Magnetic flux leakage in-line inspection

- Magnetic in-line inspection methods are indirect methods
- A well trained personnel is required
- A collection of pipe spools from field is required
- A substantial number of defects digging study is required
- The resolution and accuracy of ILI tools indirectly depends on number of sensors
- Different types of magnetizations have to be used



Ultrasound inspection

- UT is direct method
- The wave length should be at least two times smaller then the size of object and more then five times smaller then the pipe wall thickness
- The direction of sound wave have to be 45 degrees to the vertical in case of SCC detection





EMAT

Is it direct inspection method?



Electro-magnetic acoustic transformation

- The sound waves are excited in thin layer at pipe surface by means of electro-magnetic acoustic transformation
- The received direct signal is 1000 times smaller then initial one
- EMAT is extremely power consuming method
- There is strong dependence of direction of optimal sound wave excitation vs. wave length
- There is no need for accurate surface preparation and pipeline cleaning



EMAT 45^{0} impulse energy λ dependence



Electro-magnetic acoustic transformation

- The optimal wave length is 10 mm, which is comparable with pipe wall thickness
- The sound waves produced by EMA are guided resonance waves
- The form and amplitude of response signal is strongly depends on pipe wall thickness
- Different types of defects can give same signal







EMAT in-line inspection

- EMAT in-line inspection is indirect method
- A well trained personnel is required
- A collection of pipe spools from field is required
- A substantial number of defects digging study is required
- The resolution and accuracy of ILI tools indirectly depends on number of sensors
- Different types of sound waves direction and types have to be used





EMAT

SNG experience



G1Run (24") (2007)











24" Gas Pipeline









Echo EMA Anomalies

ILI Inspections Plots

SCC (2%)

LAMINATIONS (15%)

ROLLED NON-METALLIC INCLUSION (83%)









Comparison of Inspection Plots

EMAT - SCC & Inclusions in 24" pipe





TGS – ARGENTINA 2011 / EMAT

G3 Generation EMAT – 24" Model: 2010





TGS – ARGENTINA 2011 / EMAT

Condition of the tool after running!





Excavations

Argentina 2011





TGS – ARGENTINA 2011 / EMAT High PH SCC





TGS – ARGENTINA 2011 / EMAT High PH SCC













HF EMA Technologies Combined EMA/MFL, EMA/TFI ILI Tools G4 EMA Tools (Models: 2012)



EMA/MFL-30" (2012) G4

The aim is

*Detection and sizing **metal loose** defects by **MFL** and **MFL**+ *Detection and sizing **transverse crack like** defects by **MFL** *Detection and sizing **metal loose** defects by **EMA** ***Inclusions** identification by **EMA**

Channels

- 768 MFL sensors (distance between 3 mm)
- 768 Introscope sensors (distance between 3 mm)
- 336 EMA HF sensors (distance between 6,3 mm)
- 48 EC quality control sensors



EMA/TFI-30" (2012) G4

The aim is

*Detection and sizing **metal loose** defects by **TFI** *Detection and sizing **axial crack like** defects by **TFI** *Detection and sizing **axial & transverse crack like** defects by **EMA**

*Coating disbondment detection by EMA

Channels

- **1024** TFI sensors (distance between 2,6 mm)
- 64 EMA crack detection sensors. SV Mode
- 64 EMA coating disbondment sensors. SV Mode
- 256 EMA crack detection sensors. SH Mode
- 64 EMA coating disbondment sensors. SH Mode
- 64 EC quality control sensors





IF it is NO SCC

Is any sense to use EMAT?

